

# System Sleep vs Runtime Power Management

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## Definition Of Terms

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Hibernation is not covered by what follows, so “system sleep” means “the state entered by suspending to RAM”.

“Remote wakeup” is a mechanism by which suspended devices signal that they should be resumed because of an external event possibly requiring attention.

# Two Flavors of Power Management

## Runtime power management (Runtime PM)

Turn off (stop clocks or remove power) hardware components that are idle at the moment and aren't going to be used in the near future, **transparently** from the user space's viewpoint.

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## Principle

If both of them are going to be used on a given platform, subsystems and drivers need to support both **explicitly**.

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## Rules

- 1 System suspend can happen at any time.
- 2 It should put the system into the deepest (lowest-power) state possible
  - in which the contents of RAM is preserved and
  - from which the system can be woken up in (a) specific way(s).
- 3 System suspend and resume should be as fast as reasonably possible.

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However, since the freezer makes user space do nothing

User space is not available during system suspend and resume (e.g. do not request firmware or probe devices at those times).



# Suspend Sequence

- 1 Call notifiers (while user space is still there).
- 2 Freeze tasks.
- 3 1st phase of suspending devices (`.suspend()` callbacks).
- 4 Disable device interrupts.
- 5 2nd phase of suspending devices (`.suspend_noirq()` callbacks).
- 6 Disable non-boot CPUs (using CPU hot-plug).
- 7 Turn interrupts off.
- 8 Execute system core callbacks.
- 9 Turn off the CPU (possibly arm wakeup signals).

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Disabling non-boot CPUs after suspending I/O devices is necessary on ACPI-based systems.

# Resume Sequence

- 1 (Wakeup signal.)
- 2 Run boot CPU's wakeup code.
- 3 Execute system core callbacks.
- 4 Turn interrupts on.
- 5 Enable non-boot CPUs (using CPU hot-plug).
- 6 1st phase of resuming devices (`.resume_noirq()` callbacks).
- 7 Enable device interrupts.
- 8 2nd phase of suspending devices (`.resume()` callbacks).
- 9 Thaw tasks.
- 10 Call notifiers (when user space is back).

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Well, the problem is not the hardware, it is the freezing of tasks.

“Hmm, perhaps I don’t need to freeze tasks ...”

Yes, you do. There are too many ways in which user space may interact with drivers for the drivers to intercept all of them without concurrency issues (e.g. deadlocks, races).



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Power break even for the whole system is difficult to estimate.

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For runtime PM to work, all those timer/clock devices and all devices with remote wakeup capabilities should wake up.

User space decides which devices will wake up from system sleep and that may interfere (destructively) with “opportunistic” system sleep.



# CPUidle

## Put idle CPUs into low-power states (no code execution)

- CPU scheduler knows when a CPU is idle.
- Next usage information from clock events.
- Maximum acceptable latency from PM QoS.
- CPU low-power states (C-states) characteristics are known.
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CPU scheduler may take the “power topology” information into account (work in progress).

# I/O Runtime PM

## Framework for device runtime PM

- 1 Subsystems and drivers provide callbacks
  - `.runtime_suspend(dev)`
  - `.runtime_resume(dev)`
  - `.runtime_idle(dev)`
- 2 Subsystems and drivers handle remote wakeup.
- 3 The core handles concurrency (locking etc.).
- 4 The core takes care of device dependencies (parents vs children).
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Subsystem callbacks may be overridden by power management domain callbacks (representation via `struct dev_pm_domain`).

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System suspend's handling of wakeup devices is generally different from the runtime PM's one.

There are other reasons (see the changelog of commit "*PM: Limit race conditions between runtime PM and system sleep*").

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## Conclusion

Often `.runtime_suspend()` and `.suspend_noirq()` can point to the same routine, while `.suspend()` is specific to system suspend.

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System sleep means “stay in the low power state indefinitely”, so the lowest-power state available can always be used.

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The system sleep framework is not suitable for implementing runtime PM and the runtime PM framework is not suitable for implementing system suspend callbacks.

# References

-  R. J. Wysocki, *Runtime Power Management in the PCI Subsystem* ([http://www.linuxplumbersconf.org/2010/ocw/system/presentations/279/original/PCI\\_runtime\\_PM.pdf](http://www.linuxplumbersconf.org/2010/ocw/system/presentations/279/original/PCI_runtime_PM.pdf)).
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# Documentation And Source Code

- Documentation/power/devices.txt
- Documentation/power/runtime\_pm.txt
- Documentation/power/pci.txt
- include/linux/cpuidle.h
- include/linux/device.h
- include/linux/pm.h
- include/linux/pm\_domain.h
- include/linux/pm\_runtime.h
- include/linux/pm\_wakeup.h
- include/linux/suspend.h
- drivers/base/power/
- drivers/cpuidle/
- kernel/power/